

Problem Set 3

Analysis I: Multivariate Differentiation and Integration

Exercise 1: Important Objects of Differential Calculus

Consider $x_0 \in X \subseteq \mathbb{R}^n$, $f : X \mapsto \mathbb{R}$.

What is the type (e.g., real number, matrix, function, operator, etc.) of the following objects:

$\frac{\partial f}{\partial x_1}(x_0)$, $\frac{df}{dx}$, $\frac{\partial}{\partial x_1}$, f , ∇f , $\frac{df(x_0)}{dx}$

$\frac{df}{dx}(x_0)$

Value	Function
$\frac{\partial f}{\partial x_1}(\underline{x_0}) \in \mathbb{R}$	$\frac{df}{dx}, \nabla f$

$\frac{\partial f}{\partial x}(\underline{x_0}) \in \mathbb{R}^n$

Operator
 $\frac{\partial}{\partial x_1} : D_1 \rightarrow F(\mathbb{R}, \mathbb{R})$

Exercise 2: Invertability

a.) Monotonic Functions and Injectivity

Show that any strictly monotonic function is injective.

Hint: It may be helpful to look up the formal definitions of strict monotonicity and injectivity.

$$\mathbb{R} \rightarrow \mathbb{R}$$
$$x > y \Rightarrow f(x) > f(y)$$

Monotone $\Rightarrow$ injective

By contradiction

Absurd hypothesis

Assume $\exists x \neq y$ s.t. $f(x) = f(y)$

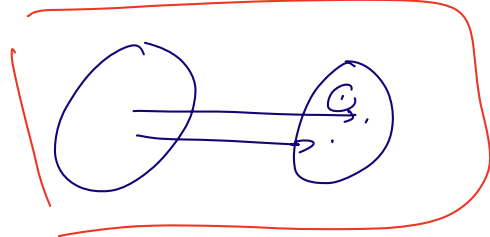
If $x \neq y \Rightarrow x > y$ or $y > x$

WLOG

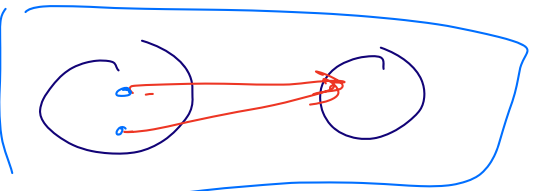
without loss of generality

$$x > y \stackrel{\text{non.}}{\Rightarrow} f(x) > f(y)$$
$$\Rightarrow f(x) \neq f(y)$$

injective $\checkmark$



Injectivity



Contradiction $\perp$

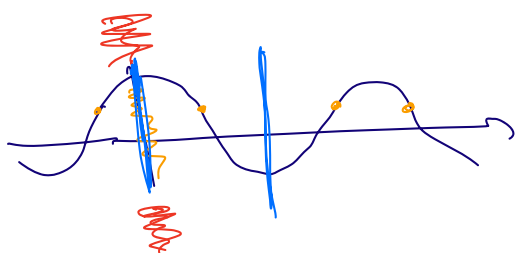
b.) Some Examples

Determine which of the following functions are invertible, and if not, which criterion (injectivity or surjectivity) fails. In case of non-invertibility, can you restrict the domain and/or codomain to achieve invertability?¹ $\leftrightarrow$ bijective function (one-to-one)

1. $f: \mathbb{R} \rightarrow \mathbb{R}, x \mapsto \cos(x)$
2. $f: \mathbb{R} \rightarrow \mathbb{R}, x \mapsto x^2$
3. $f: \mathbb{N} \rightarrow \mathbb{N}, n \mapsto n^4$
4. $f: \mathbb{R} \rightarrow \mathbb{R}, x \mapsto \mathbb{1}[x < 1](x-1)^2 + \mathbb{1}[x \geq 1]\log(x)$ $= \begin{cases} (x-1)^2 & x < 1 \\ \log x & x \geq 1 \end{cases}$

Hint: for 4., investigate the two parts of the domain, $x < 1$ and $x \geq 1$, separately, and then think about whether putting the two parts together changes your conclusion. It may also be helpful to draw the function.

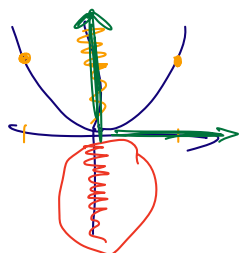
1. $f: \mathbb{R} \rightarrow \mathbb{R} \quad x \mapsto \cos x$



$$f: [0, \pi] \rightarrow [-1, 1]$$

2. $f: \mathbb{R} \rightarrow \mathbb{R}: x \mapsto x^2$

$$f^{-1} = \sqrt{x}$$

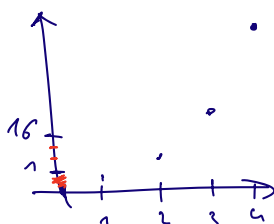


$$f: \mathbb{R}_0^+ \rightarrow \mathbb{R}_0^+: x \mapsto x^2$$

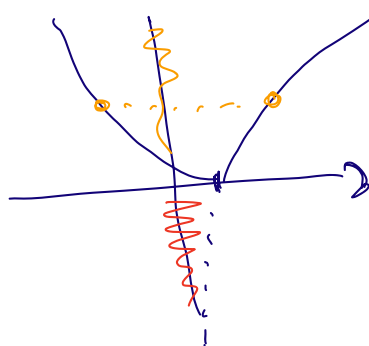
3. $f: \mathbb{N} \rightarrow \mathbb{N}: n \mapsto n^4$

$$= \text{im } f = f(\mathbb{N})$$

$$f: \mathbb{N} \rightarrow \{n \in \mathbb{N} : \exists k \in \mathbb{N} \ n = k^4\}$$



4. $f: \mathbb{R} \rightarrow \mathbb{R} \quad x \mapsto \begin{cases} (x-1)^2 & x < 1 \\ \log x & x \geq 1 \end{cases}$



$$f: (-\infty, 1) \rightarrow \mathbb{R}_0^+ \quad (x-1)^2$$

$$f: [1, \infty) \rightarrow \mathbb{R}_0^+ \quad \log x$$

¹You should understand the word "restrict" as cutting the set to the left/right, but do not manipulate it in the middle; e.g. if the initial set is $\mathbb{N}$, then $R = \mathbb{N} \cap [3, 100]$ is an allowed restriction, but $R = \{3, 9, 27, 87\}$ is not.

Exercise 3: Convexity

Investigate the following function with respect to (strict) convexity/concavity:

$$f: \mathbb{R}^n \mapsto \mathbb{R}, x \mapsto \|x\|$$

3. $\|a+b\| \leq \|a\| + \|b\|$
2. $\|\alpha a\| = |\alpha| \cdot \|a\|$

where $\|\cdot\|$ is a norm on $\mathbb{R}^n$, $n \in \mathbb{N}$.

Hint 1: Some universal properties of norms might be helpful.

Hint 2: A function is only both convex and concave if it is linear, i.e. $f(x+y) = f(x) + f(y)$ for any possible arguments x, y . Thus, once you showed that f satisfies one of the properties, you can check the other by investigating whether f is/can potentially be linear.

WTS: Condition convexity

$$\lambda \in [0, 1]$$

$$f(\lambda x + (1-\lambda)y) \leq \lambda f(x) + (1-\lambda)f(y)$$

$$\|\lambda x + (1-\lambda)y\| \leq \lambda \|x\| + (1-\lambda)\|y\|$$

$$\begin{aligned} \underbrace{\|\lambda x + (1-\lambda)y\|}_{v_1} &\stackrel{\text{Triangle ineq.}}{\leq} \underbrace{\|\lambda x\|}_{v_2} + \|(1-\lambda)y\| \\ &= \text{Homog.} = |\lambda| \|x\| + |1-\lambda| \|y\| \\ &= \lambda \|x\| + (1-\lambda)\|y\| \end{aligned}$$

→ (weak) convexity

str. convexity ✗ $x=0$

$$\begin{aligned} \|\lambda 0 + (1-\lambda)y\| &= (1-\lambda)\|y\| \\ &= \lambda \cdot 0 + (1-\lambda)\|y\| \end{aligned}$$

(weak) concavity ✗ $x = -y \quad \lambda = \frac{1}{2}$

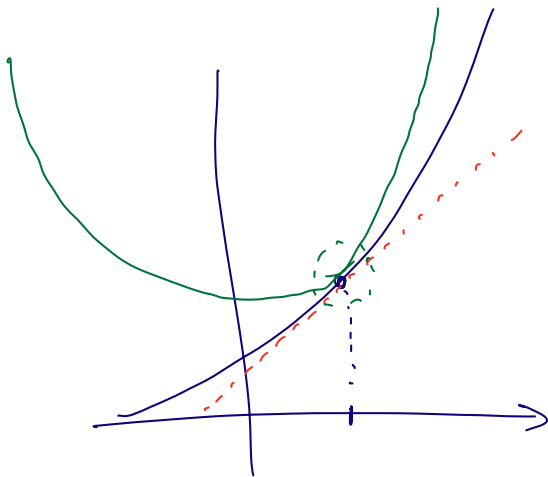
$$\|\lambda x + (1-\lambda)y\| = \|\frac{1}{2}x - \frac{1}{2}x\| = \|0\| < \frac{1}{2}\|x\| + \frac{1}{2}\|y\|$$

Exercise 4: Multivariate Differentiation

a.) Taylor Approximation: Univariate case

This exercise is meant as a fresh up for Taylor's theorem. Feel free to skip ahead to (b) if you are already well-familiar with Taylor approximations.

Compute the first and second order Taylor approximations to the exponential function $\exp : \mathbb{R} \mapsto \mathbb{R}_+, x \mapsto \exp(x)$ around $x_{0,1} = 1$. Evaluate both approximations at $x = -5$ and $x = 2$. Is one always better than the other? Are the approximations "good", i.e. are they close to the true value?



$$\begin{aligned} T_{1,x_0} &= f(x_0) + f'(x_0)(x - x_0) \\ &= e^{x_0} + e^{x_0}(x - x_0) \end{aligned}$$

$$\begin{aligned} T_{2,x_0} &= f(x_0) + f'(x_0)(x - x_0) + \frac{1}{2}f''(x_0)(x - x_0)^2 \\ &= e^{x_0} + e^{x_0}(x - x_0) + \frac{1}{2}e^{x_0}(x - x_0)^2 \end{aligned}$$

$$f(x) = e^x \quad f' = f'' = f^{(n)} = e^x$$

$$T_{1,x_0}(2) = e + e(2-1) = 2e$$

$$T_{1,x_0}(-5) = e + e(-5-1) = -5e$$

$$T_{2,x_0}(2) = e + e(2-1) + \frac{1}{2}e(2-1)^2 = \frac{5}{2}e \quad T_{2,x_0}(-5) = e + e(-5-1) + \frac{1}{2}e(-5-1)^2 = 13e$$

$$e^2 \approx 2.718 \dots e$$

$$e^{-5} \approx 0.0067$$

b.) Matrix Functions

Consider a matrix $A \in \mathbb{R}^{n \times n}$, $n \in \mathbb{N}$.

(i) Show that $\frac{d}{dx}(Ax) = A$.

(ii) What is the derivative of $f: \mathbb{R}^n \mapsto \mathbb{R}, x \mapsto x'Ax$?

Hint: Use (i) and the multivariate product rule.

(iii) If $A = \begin{pmatrix} 1 & \alpha \\ \beta & 4 \end{pmatrix}$, can you find values for α and β so that the second derivative of $x'Ax$ is positive definite everywhere? Can you find an alternative combination where A is positive semi-definite but not positive definite?

$$\left(\begin{pmatrix} 2 & \alpha+\beta \\ \alpha+\beta & 8 \end{pmatrix} x \right)'$$

$$= x'Ax \rightarrow x' \begin{pmatrix} 2 & \alpha+\beta \\ \alpha+\beta & 8 \end{pmatrix}$$

$$\frac{d^2}{dx^2} = \begin{pmatrix} 2 & \alpha+\beta \\ \alpha+\beta & 8 \end{pmatrix}$$

$$\det = 2 \cdot 8 - (\alpha+\beta)^2 > 0 \quad (\alpha+\beta)^2 < 16 \quad |\alpha+\beta| < 4$$

$$(i) \quad \underline{Ax} = \begin{pmatrix} a_{11} \\ \vdots \\ a_{1n} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} a_{11}x_1 \\ \vdots \\ a_{1n}x_n \end{pmatrix} \rightarrow J_{Ax} = \begin{pmatrix} \nabla a_{11}x \\ \vdots \\ \nabla a_{1n}x \end{pmatrix}$$

$$\nabla a_{1i}x = \nabla (a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n)$$

$$\nabla = [a_{11} \quad a_{12} \quad \dots \quad a_{1n}]$$

$$J_{Ax} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} = A$$

$$ii) \quad \frac{d}{dx} x'Ax$$

$$f(x) = ax^2$$

$$\frac{d}{dx} f^T g = f^T \frac{d}{dx} g + g^T \frac{d}{dx} f$$

$$= x' I_n' A x \Rightarrow \frac{d}{dx} (I_n x)' (Ax)$$

$$= (I_n x)' A + (Ax)' I_n$$

$$= x' I_n A + x' A' I_n = x' A + x' A'$$

$$= x' (A + A')$$

Symmetric $A \quad x' (A + A') = \underline{2x'A}$

$$f'(x) = 2ax$$

Exercise 5: Multivariate Differentiation

a.) Hessian Criterion for Convexity

Investigate the following function with respect to (strict) convexity/concavity:

$$f: \mathbb{R}^2 \mapsto \mathbb{R}, x = (x_1, x_2)' \mapsto \exp(x_1) + x_1 x_2 + 5x_1 + 4$$

Hint: Recall that we can use the second derivative to investigate convexity. The function is infinitely many times continuously partially differentiable, which can save you a few computational steps.

$$f(x_1, x_2) = e^{x_1} + x_1 x_2 + 5x_1 + 4$$

$$\nabla f = \begin{pmatrix} e^{x_1} + x_2 + 5 & x_1 \end{pmatrix}$$

$$H_f = \begin{pmatrix} e^{x_1} & 1 \\ 1 & x_1 \end{pmatrix}$$

$\det = e^{x_1} \cdot x_1 - 1 = -1 < 0$

not pos. or neg. definite

b.) Support Restriction?

Use the Hessian Criterion to investigate whether the function

$$f(x_1, x_2) = \frac{1}{2}(x_2^3 + 2x_1x_2 + x_1^2)$$

is (strictly) convex or concave on $\mathbb{R}^3$, and otherwise try to find the support restrictions on which one of the properties holds.

Hint: The function is infinitely many times continuously partially differentiable, which can save you a few computational steps.

$$f(x_1, x_2) = \frac{1}{2}(\underline{x_1^2} + \underline{2x_1x_2} + \underline{x_2^3})$$

$$\nabla f = \left(\begin{array}{c} x_1 + x_2 \\ x_1 + \frac{3}{2}x_2^2 \end{array} \right)$$

$$H_f = \begin{pmatrix} 1 & 1 \\ 1 & 3x_2 \end{pmatrix} \quad \begin{array}{l} \text{det} > 0 \\ \text{det} = 3x_2 - 1 \geq 0 \end{array}$$

$$3x_2 - 1 > 0$$

$$3x_2 > 1 \Leftrightarrow x_2 > \frac{1}{3}$$

$$f: \mathbb{R} \times \left(\frac{1}{3}, \infty\right) \rightarrow \mathbb{R} \quad \text{str. convex}$$

Exercise 6: Multivariate Integration

Consider an economy populated by a mass $[0, 1]$ of firms that use capital k and labor l to produce output $y = f(k, l) = Ak^\alpha l^{1-\alpha}$, i.e. they use the same Cobb-Douglas production technology. Further, suppose that economy-wide output satisfies

$$Y = \int_{[0,1] \times [0,1]} f(k, l) d(k, l).$$

Amongst others, this relationship can be obtained from assuming that labor l and capital k are independently and uniformly distributed on $[0, 1]$. However, it is not too important what this means here, it just ensures that the equality above holds.

Determine Y as a function of A and α . What do you conclude for the role of α , the relative importance of capital in the production process in terms of its relationship to Y ?

$$f(k, l) = Ak^\alpha l^{1-\alpha}$$

$$\int_{[0,1] \times [0,1]} Ak^\alpha l^{1-\alpha} d(k, l)$$

$$\begin{aligned} & \int_{[0,1]} \underbrace{Al^{1-\alpha}}_{Al^{1-\alpha} \frac{1}{\alpha+1}} \int_{[0,1]} k^\alpha dk dl \\ & A \frac{1}{\alpha+1} \int_0^1 l^{1-\alpha} dl \\ & A \frac{1}{\alpha+1} \frac{1}{2-\alpha} \end{aligned}$$

$$f(x) = g(x_1, \dots, x_k) h(x_{k+1}, \dots, x_n) \quad \int g \cdot \int h$$

$$A \int_0^1 k^\alpha dk \int_0^1 l^{1-\alpha} dl = A \left[\frac{1}{\alpha+1} k^{\alpha+1} \right]_0^1 \left[\frac{1}{2-\alpha} l^{2-\alpha} \right]_0^1$$

$$= A \frac{1}{\alpha+1} \cdot \frac{1}{2-\alpha} = \frac{A}{(\alpha+1)(2-\alpha)} = \frac{A}{2-\alpha^2+\alpha}$$